



# Maps of manifolds

Let  $M$  and  $N$  be manifolds and let  $\phi: M \rightarrow N$  be a  $C^\infty$  map.

1) In "natural manner" or "pulls back" a func.  $f: N \rightarrow \mathbb{R}$  on  $N$  to the func  $f \circ \phi: M \rightarrow \mathbb{R}$  obtained by composing  $f$  with  $\phi$

2)  $\phi$  "carries along" tangent vec at  $p \in M$  to tangent vec at  $\phi(p) \in N$   
 ↳ it defines a map  $\phi^*: V_p \rightarrow V_{\phi(p)}$  → For  $v \in V_p$  we define  $\phi^*v \in V_{\phi(p)}$  by

$$(\phi^*v)(f) = v(f \circ \phi) \quad \forall f: N \rightarrow \mathbb{R}$$

where  $f$  is  $C^\infty$

Note:  $\phi^*$  is linear and may be viewed as the "derivative of  $\phi$ " at  $p$ .

Remark: The matrix of components of  $\phi^*$  in the coord. basis of a coord. sys  $\{\bar{x}^i\}$  at  $p$  and a coord sys.  $\{\bar{y}^j\}$  at  $\phi(p)$  equals the Jacobian mtr of the map  $\phi$  between the coord.; i.e.,  $(\phi^*)^{ij} = \partial y^i / \partial x^j$ .

By the implicit func. theorem,  $\phi: M \rightarrow N$  will be one-to-one in a neighborhood of  $p$  if  $\phi^*: V_p \rightarrow V_{\phi(p)}$  is one-to-one.

3) We can use  $\phi$  to "pull back" dual vec. at  $\phi(p)$  to dual vec. at  $p$ . We define the map  $\phi_*: V_{\phi(p)}^* \rightarrow V_p^*$  by requiring that  $\phi^*v \in V_p^*$

$$(\phi_*v)_a v^a = v_a (\phi^*v)^a$$

We can extend the action of  $\phi_*$  to map tensors of type  $(0, l)$  at  $\phi(p)$  to tensors of type  $(0, l)$  at  $p$  by

$$(\phi_*T)_{a_1 \dots a_l} (v^1)^{a_1} \dots (v^l)^{a_l} = T_{a_1 \dots a_l} (\phi^*v^1)^{a_1} \dots (\phi^*v^l)^{a_l}$$

Similarly for tensors of type  $(k, 0)$

$$(\phi^*T)^{b_1 \dots b_k} (u_1)_{b_1} \dots (u_k)_{b_k} = T^{b_1 \dots b_k} (\phi_*u_1)_{b_1} \dots (\phi_*u_k)_{b_k}$$

Remark: We cannot extend  $\phi^*$  or  $\phi_*$  to mixed tensors since  $\phi^*$  doesn't know how to "carry along" lower index tensors, while  $\phi_*$  doesn't know how to "pull back" upper index tensors.

A  $C^\infty$  map  $\phi: M \rightarrow N$  is said to be a diffeomorphism if it is one-to-one, onto, and its inverse is  $C^\infty$  if  $\phi$  is diffeomorphism  $\Rightarrow$  we can use  $\phi^{-1}$  to extend the definition of  $\phi^*$  to tensors of all types by using the fact that  $(\phi^{-1})^*$  goes from  $V_{\phi(p)}$  to  $V_p$ . If  $T^{b_1 \dots b_k}_{a_1 \dots a_l}$  is a tensor of type  $(k, l)$  at  $p$ , we define the tensor  $(\phi^*T)_{a_1 \dots a_l}^{b_1 \dots b_k}$  at  $\phi(p)$  by

$$(\phi^*T)_{a_1 \dots a_l}^{b_1 \dots b_k} (u_1)_{b_1} \dots (u_k)_{b_k} (t^1)^{a_1} \dots (t^l)^{a_l} = T^{b_1 \dots b_k}_{a_1 \dots a_l} (\phi_*u_1)_{b_1} \dots (\phi_*u_k)_{b_k} ((\phi^{-1})^*t^1)^{a_1} \dots ((\phi^{-1})^*t^l)^{a_l}$$

Remark: Similarly, we could extend the map  $\phi_*$  to all tensors. However, it is not difficult to show that  $\phi_* = (\phi^{-1})^*$ .

If  $\phi: M \rightarrow M$  is diffeomorphism and  $T$  is a tensor field on  $M$ , we can compare  $T$  with  $\phi^* T$ . If  $\phi^* T = T \Rightarrow$  "moved"  $T$  via  $\phi$  and "stayed the same"  $\Rightarrow \phi$  is a symmetry transformation for  $T$ .

Remark: For the metric  $g$  a symmetry trans. is called an isometry.

Remark: If  $\phi: M \rightarrow N$  is a diffeomorphism  $\Rightarrow M$  &  $N$  have identical manifold structure.

If a theory describes nature in terms of a space-time manifold,  $M$ , and tensor fields,  $T^{(i)}$ , defined on the manifold, then if  $\phi: M \rightarrow N$  is a diffeomorphism, the solutions  $(M, T^{(i)})$  and  $(N, \phi^* T^{(i)})$  have physically identical properties.

## Lie derivative

Let  $M$  be a manifold and let  $\phi_t$  be a one-parameter group of diffeomorphisms.  $\phi_t$  will be generated by a vectorfield  $v^a$  and  $\phi_t^*$  carries along  $C^\infty$  tensorfield  $T^{a_1 \dots a_k}$ . Comparison of  $T^{a_1 \dots a_k}$  and  $\phi_{-t}^* T^{a_1 \dots a_k}$  for small  $t$  gives rise to the notion of Lie derivative,  $L_v$ , with respect to  $v^a$ . More precisely:

$$L_v T^{a_1 \dots a_k} = \lim_{t \rightarrow 0} \left\{ \frac{\phi_t^* T^{a_1 \dots a_k} - T^{a_1 \dots a_k}}{t} \right\}$$

where all tensors appearing are evaluated at the same point  $p$ .

Note: index on  $v^a$  is dropped in the symbol  $L_v$  since it presence could lead to confusion.

Properties of Lie derivative:

- (i) If  $\mathcal{T}(E, C)$  be a group of  $C^\infty$  type  $(E, C)$  tensor fields.  $L_v: \mathcal{T}(E, C) \rightarrow \mathcal{T}(E, C)$  is a linear map.
- (ii)  $L_v$  satisfies the Leibnitz rule on outer products of tensors

$$L_v(T \cdot R) = T \cdot L_v R + R \cdot L_v T$$

- (iii) Since  $v^a$  tangent to the integral curves of  $\phi_t$ , for func.  $f: M \rightarrow \mathbb{R}$  we have

$$L_v(f) = \mathcal{O}(f)$$

- (iv)  $L_v$  commutes with the contraction

- (v)  $L_v T^{a_1 \dots a_k} = 0$  everywhere IFF  $\phi_t: \phi_t$  is a symmetry trans. for  $T$ .

The components of  $\mathcal{L}_v$  of  $T^{a_1 \dots a_k}_{b_1 \dots b_k}$  in a coord. sys. adapted to  $\sigma^a$  are simply

$$\mathcal{L}_v T^{a_1 \dots a_k}_{b_1 \dots b_k} = \frac{\partial T^{a_1 \dots a_k}}{\partial x^1}. \quad (\ast)$$

Thus in particular,  $\phi^*_v$  will be a symmetry trans. of  $T$  iff the components  $T^{a_1 \dots a_k}_{b_1 \dots b_k}$  in a coord. sys. adapted to  $\sigma^a$  are independent of the integral curve coordinate  $x^1$ . We can obtain a coord. independent expression for  $\mathcal{L}_v$  of a vec. field  $v^a$  by noting that in an adapted coord. sys., we have by eq. ( $\ast$ )

$$\mathcal{L}_v w^a = \frac{\partial w^a}{\partial x^1}$$

Since  $v^a = (\partial/\partial x^1)^a$  and  $w^a = \sum_m w^m (\partial/\partial x^m)^a$ , the commutator of  $v^a$  and  $w^a$ :

$$[v, w]^a = \sum_p \left( v^a \frac{\partial w^p}{\partial x^p} - w^p \frac{\partial v^a}{\partial x^p} \right) = \frac{\partial w^a}{\partial x^1}$$

$$\mathcal{L}_v w^a = [v, w]^a$$

coord. sys. independent formula for Lie derivative.

The action of Lie derivative on all other types of tensor fields is determined by prop. (iii), and  $\mathcal{L}_v w^a = [v, w]^a$ , and the Leibnitz rule.

E.G.: for dual vec. field,  $\mu_a$ , we have by prop. (iii)

$$\mathcal{L}_v (\mu_a w^a) = v (\mu_a w^a)$$

where  $w^a$  is an arbitrary field. By the Leibnitz rule and  $\mathcal{L}_v w^a = [v, w]^a$ , we have

$$\mathcal{L}_v (\mu_a w^a) = w^a \mathcal{L}_v \mu_a + \mu_a [v, w]^a$$

If  $P_a$  is a der. op. on  $M$ , we have by prop. (4) and (7) of the definition der. op.

$$v(\mu_a w^a) = v^b P_b (\mu_a w^a) = v^b w^a P_b \mu_a + v^b \mu_a P_b w^a$$

$$[v, w]^a = v^b P_b w^a - w^b P_b v^a$$

$$v^b w^a P_b \mu_a + v^b \mu_a P_b w^a = w^a \mathcal{L}_v \mu_a + \mu_a v^b P_b w^a - \mu_a w^b P_b v^b$$

$$\mathcal{L}_v \mu_a = v^b P_b \mu_a + \mu_a P_b v^b$$

More generally for an arbitrary tensor field:

$$\mathcal{L}_v T^{a_1 \dots a_k}_{b_1 \dots b_k} = v^c P_c T^{a_1 \dots a_k}_{b_1 \dots b_k} - \sum_{i=1}^k T^{a_1 \dots a_k}_{b_1 \dots b_k} P_i v^{a_i} + \sum_{j=1}^k T^{a_1 \dots a_k}_{b_1 \dots c \dots b_k} P_{b_j} v^c$$

If  $\phi: M \rightarrow M$  diffeomorphism  $\Rightarrow (M, g_{ab})$  and  $(M, \phi^* g_{ab})$  represent the same physical space-time. If we consider 1-parameter family of space-times  $(M, g_{ab}(t))$  and  $(M, \phi_t^* g_{ab}(t))$  represent the same 1-parameter family, where  $\phi_t^*$  is an arbitrary 1-parameter group of diffeomorphisms.

If we consider the 1st order perturbation of  $\text{gas}_{A=0}$  we obtained by differentiating gas (A) with respect to A at A=0, we find that  $P_{ab} = \partial g_{ab}/\partial A|_{A=0}$  and  $P_{ab} = d(\phi_t^* \text{gas})/dA|_{A=0}$  represent the same perturbation.

$$M_{ab} \rightarrow P_{ab} - P_a v_b$$

$v^a$  is the vec. field which generates  $\phi_t^*$  and  $\text{gas} = \text{gas}(A=0)$ . Thus, the gauge freedom in perturbation  $M_{ab}$  is given by  $\text{Logas}$ , where  $v^a$  is an arbitrary vec. field.

$$\begin{aligned}\text{Logas} &= v^c P_c g_{ab} + g_{ab} P_a v^c + g_{ac} P_b v^c \\ &= P_a v_b + P_b v_a\end{aligned}$$

Thus, the gauge transformation of linearized GR, about a solution  $g_{ab}$  are

$$M_{ab} \rightarrow M'_ab = M_{ab} - P_a v_b - P_b v_a$$

This is closely analogous to the gauge freedom  $A_a \rightarrow A'_a - P_a X$  of electromagnetism.

## Killing Vector Fields

If  $\phi_t: M \rightarrow M$  is 1-parameter group of isometries,  $\phi_t^* \text{gas} = \text{gas}$ , the vec. field  $\xi^a$  which generates  $\phi_t$  is called a Killing vec. field. The necessary and sufficient condition for  $\phi_t$  to be a group of isometries is  $\text{Logas} = 0$ . Thus, according to  $\text{Logas} = P_a v_b - P_b v_a$  the necessary and sufficient cond. that  $\xi^a$  be a Killing vec. field is that it satisfy Killing's equation:

$$P_a \xi_b + P_b \xi_a = 0$$

Proposition: If  $\xi^a$  be a Killing vec. field and let  $\gamma$  be a geodesic with tangent  $u^a$ . Then  $\xi_a u^a$  is constant along  $\gamma$ .

Proof: We have

$$u^b P_b (\xi_a u^a) = u^b u^a P_b \xi_a + \xi_a u^b P_b u^a = 0$$

since the first term vanishes by Killing's equation and the second term vanishes by the geodesic equation. It

Since in GR timelike geodesic represent the spacetime motions of freely falling particles and null geodesic represent the paths of light rays, this prop. can be interpreted as saying that every 1-parameter family symmetries gives rise to a conserved quantity for particles and light rays. This conserved quantity

enables one to determine the gravitational redshift in stationary spacetimes and is extremely useful for integrating the geodesic eq. when symmetries are present.

### The Reimann tensor:

$$D_a D_b \xi_c - D_b D_a \xi_c = R_{abc}{}^d \xi_d \quad / \text{Killing eq.}$$

$$D_a D_b \xi_c + D_b D_c \xi_a = R_{abc}{}^d \xi_d$$

If we write down the cyclic permutation of indices  $(abc) \Rightarrow$  adding them together, we get:

$$2 D_b D_c \xi_a = (R_{abc}{}^d + R_{bac}{}^d - R_{cab}{}^d) \xi_d = -2 R_{abc}{}^d \xi_d$$

We used the symmetry properties of  $R_{abc}{}^d$ . Thus,  $\nabla^\alpha \xi_\alpha$  we obtain the formulae:

$$D_a D_b \xi_c = -R_{bca}{}^d \xi_d$$

A Killing field,  $\xi^\alpha$ , is completely determined by the values of  $\xi^\alpha$  and  $L_{ab} \equiv D_b \xi_a$  at any point p of M.

If we are given  $(\xi^\alpha, L_{ab})$  at p  $\Rightarrow (\xi^\alpha, L_{ab})$  at any other point q is determined by integration of the system of ODE

$$v^\alpha D_a \xi_b = v^\alpha L_{ab}$$

$$v^\alpha D_a L_{bc} = -R_{bac}{}^d \xi_d v^\alpha$$

along the curve connecting p and q, where  $v^\alpha$  denotes the tangent to the curve

Corollaries of this result

(i) if a Killing field and its derivative vanish at a point, then the Killing field vanishes everywhere

(ii) on a manifold of dim n, there can be at most

$$n + \frac{n(n-1)}{2} = \frac{n(n+1)}{2}$$

linearly independent Killing fields, since this is the dim of the space of initial data for  $(\xi^\alpha, L_{ab})$ .

If we contract over a and b, we find

$$D^\alpha D_a \xi_\alpha = -R_c{}^d \xi_d$$

Thus, in a vacuum space time,  $R_c{}^d = 0$ ,  $\xi^\alpha$  satisfies the sec. free Maxwell eq. for a vec. potential in the Lorentz gauge.

The Lorenz gauge condition  $D_a \xi^a = 0$ .