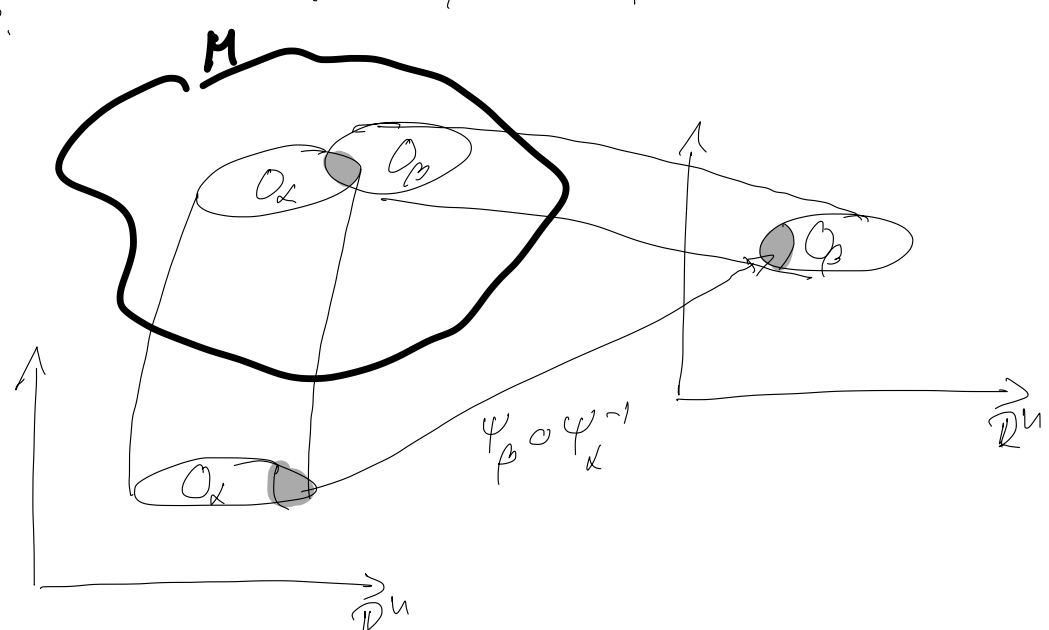




Def: A function $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is said to be class C^r , if for any of its var. it can be continuously partially differentiated r -times. This way the class of continuous functions is C^0 , while those functions that have any order of partial derivative is class C^∞ or called smooth. If the function also same as its Taylor sequence, then we call it analytical or class C^ω .

Def: The (M, \mathcal{T}) top. sp. is class C^r , n -dim, real differentiable manifold, if there for it \exists subsets of pairs of points $\{(O_\alpha, \psi_\alpha)\}$ such that they satisfying the following properties:

- (i) The seq. of sets $\{O_\alpha\}$ is open cover of M , i.e., $M \subseteq \bigcup_\alpha O_\alpha$.
- (ii) $\forall \alpha$, there is one-to-one, onto, map $\psi_\alpha: O_\alpha \rightarrow U_\alpha$, where U_α is an open subset of \mathbb{R}^n .
- (iii) If any two set O_α & O_β overlap, $O_\alpha \cap O_\beta \neq \emptyset$, we can consider the map $\psi_\beta \circ \psi_\alpha^{-1}: \psi_\alpha [O_\alpha \cap O_\beta] \rightarrow \psi_\beta [O_\alpha \cap O_\beta]$. We require these subsets of \mathbb{R}^n to be class C^∞ .



Mathematicians:

(O_α, ψ_α) chart $\rightarrow \{(O_\alpha, \psi_\alpha)\}$ atlas

Physicists:

- (O_α, ψ_α) local coord. system
- $\psi_\beta \circ \psi_\alpha^{-1}$ coord. transformation
- $\{ (O_\alpha, \psi_\alpha) \}$ maximal

In case of some (O, ψ) in stead of using ψ many times we use the coord. (x_1, \dots, x_n) expressed by it.

Examples:

1) Euclidian sp., \mathbb{R}^n (\mathbb{E}^n), provides a trivial example of manifold, which can be covered by a single chart ($O = \mathbb{R}^n$, $\psi =$ identity map)

2) 2-sphere S^2 :

$$S^2 = \{ (x^1, x^2, x^3) \in S^2 \mid \pm x^i > 0 \}$$

The entire S^2 cannot be mapped into \mathbb{R}^2 in a continous, one-to-one manner, but "pieces" of S^2 can, and these can be "smoothly" sewn together. For example, if we define the 6 hemispherical open sets O_i^\pm for $i=1,2,3$ by

$$O_i^\pm = \{ (x^1, x^2, x^3) \in S^2 \mid (x^1)^2 + (x^2)^2 \mp (x^3)^2 = 1 \}$$

then $\{O_i^\pm\}$ covers S^2 . Furthermore, each O_i^\pm can be mapped homeomorphically into the open disk $D = \{ (x, y) \in \mathbb{R}^2 \mid x^2 + y^2 < 1 \}$ in the plane via the "projections maps" $f_1^+ : O_1^+ \rightarrow D$, $f_1^- : O_1^- \rightarrow D$, etc., defined by $f_1^+(x^1, x^2, x^3) = (x^2, x^3)$, etc. The overlap func. $f_i^\pm \circ (f_j^\pm)^{-1}$ can be checked to be C^∞ in their domain of def. Thus, S^2 is a 2-dim manifold. In the similar manner, the n -dim sphere S^n is seen to be a manifold.

In case if we want to express further structure on our manifold such as metric or integration interpreted on diff. manifolds, we assume that our manifold be para-compact

Def: An atlas $\{(O_\alpha, \psi_\alpha)\}$ is said to be locally finite if every point $p \in M$ has an open neighborhood which intersects only a finite number of the sets O_α

Def: A connected Hausdorff manifold is para-compact iff it has a countable basis, i.e., there is a countable collection of open sets such that any open can be expressed as the union of members of this collection.

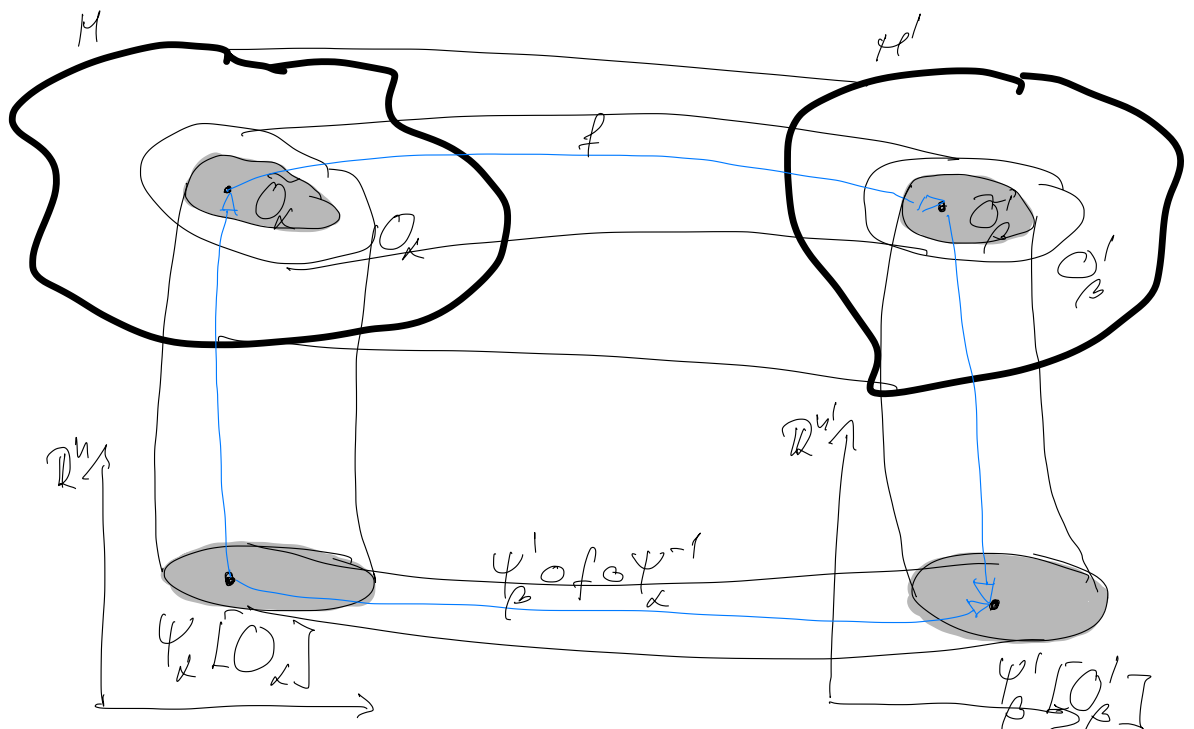
Def: Given two manifold M and M' of class C^r , a mapping $f: M \rightarrow M'$ is said to be differentiable of class C^k , $k \leq r$, if for every chart (O_α, ψ_α) of M and every chart (O'_β, ψ'_β) of M' such that $f[O_\alpha] \subset O'_\beta$, the mapping $\psi'_\beta \circ f \circ \psi_\alpha^{-1}$ of $\psi_\alpha[O_\alpha]$ into $\psi'_\beta[O'_\beta]$ is differentiable of class C^k .

Examples:

- 1) We choose M to be any subset of M . Then, by definition $f: M \subset \mathbb{R}^n \rightarrow M'$ expresses a class C^k curve in M' .
- 2) $M' = \mathbb{R}$. Then the above expression gives us the definition of class C^k of func. $f: M \rightarrow \mathbb{R}$.

Def: If M and M' be class C^r manifolds, if $f: M \rightarrow M'$ is C^r one-to-one, onto, and has C^r inverse, f is called diffeomorphic and M and M' are said to be diffeomorphic.

Remark: Diffeomorphic manifolds have identical manifold structure.



Example:

In the definition of diffeomorphism it is not enough, if we only require the $f: M \rightarrow M'$ to be one-to-one, onto, and differentiable. Because, for example the func. $f: \mathbb{R} \rightarrow \mathbb{R}$, where $f(x) = x^3$, is one-to-one, onto, and differentiable, but its inverse is not differentiable at point $f(x) = 0$.